

IRN4C-F1-V2

4 channels infrared temperature sensor with CAN bus output

SN: I#####

Texense sensors are designed for data logging. Should the users want to include this sensor in a closed loop system, they must undertake total responsibility from doing so.

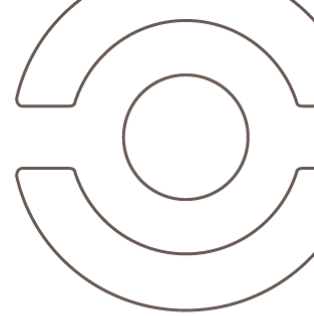
| Measurement features | | |
|-------------------------------|---|-------|
| Available ranges | -20 to +140 or -20 to +200 | °C |
| Accuracy at FS | ±1 | %FS |
| Response time at FS | 260 | ms |
| Sensitive Element | Thermopile with Silicon Lens | |
| Wave Length | 8 to 14 | µm |
| Emissivity / Distance tuning | Gain factor 0.5 to 2 configurable by CAN | |
| Field of view (90% radiation) | 6.5:1 (30mm at 200mm) | |
| Total horizontal angle | 22.5 or 41.6 | ° |
| Lens protection | Replaceable window (PEHD) | |
| Calibrator | HGHECN 100 H12 | |
| CAN bus | | |
| CAN type | 2.0A or B | |
| Output data | Calibrated temperature | |
| Resolution | 0.1 | %/bit |
| Baud rate | 125k to 1Mbps | |
| Frequency | 1Hz to 10Hz, request mode | |
| Electrical features | | |
| Supply Voltage | 6 to 16 | V |
| Supply Current | 17 | mA |
| Mechanical features | | |
| Dimensions | 31x11x17 | mm |
| Material | Aluminum | |
| Weight (without cable) | 15 | g |
| Environment | | |
| Protection | IP64 | |
| Vibration test | 20Gpp 5' | |
| Shock | 500 | G |
| Operating Temp | -20 to +85 | °C |
| Storage Temp | -40 to +125 | °C |

| | | | |
|-------------|------------------------|----------|--|
| Date | | Operator | |
| Customer | | | |
| Order | | | |
| Product Ref | IRN4C-F1-###-V2-##-### | | |
| SW version | V### | | |

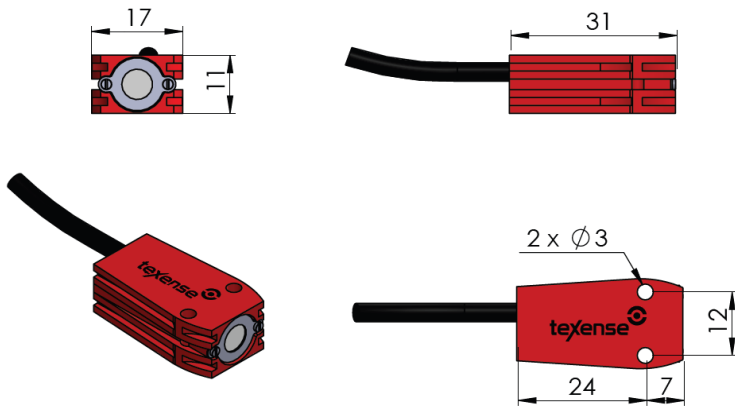
| Sensor Readings | | |
|------------------------|-------|--------|
| Calibrator Temperature | 25 °C | ... °C |
| Channel 1 | | |
| Channel 2 | | |
| Channel 3 | | |
| Channel 4 | | |

| Setup parameters | |
|-------------------------|---------|
| CAN type | 2.0A |
| Baudrate | 1Mbps |
| Frequency | 10Hz |
| Rx trig ID | 0x7F0 |
| Tx ID | 0x3F0 |
| Degree unit | Celsius |
| Gain factor | 1000 |
| Digital low pass filter | 400 ms |
| Dynamic compensation | ON |

| Hardware parameters | |
|--------------------------|--|
| CAN termination resistor | <input checked="" type="checkbox"/> Not connected |
| | <input type="checkbox"/> Connected |
| Cable | <input checked="" type="checkbox"/> 4x26AWG FEP tinned copper braided cable 250V 200°C |
| | <input type="checkbox"/> EPD116760A |



Mechanical drawing

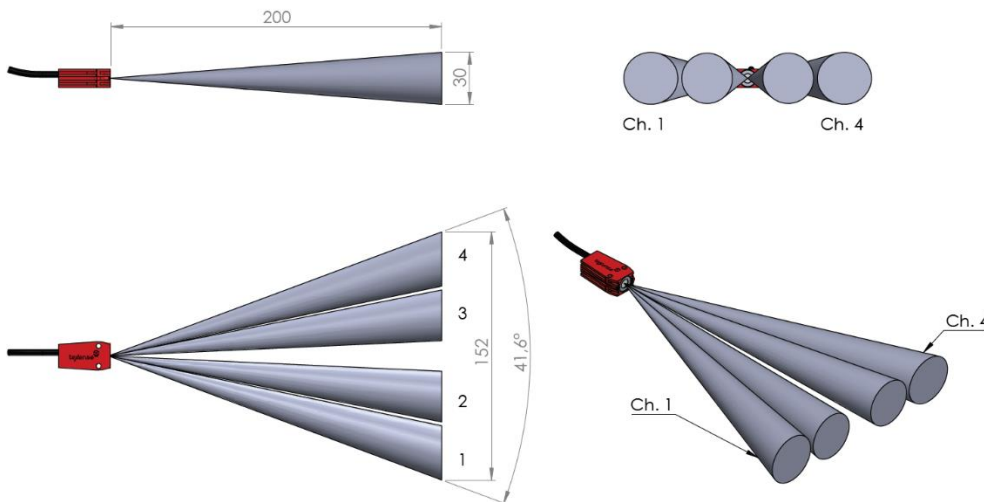


Wiring

| Cable | | |
|---|----------|--------------|
| Cable: | | |
| <ul style="list-style-type: none"> • Default: 4x26AWG FEP tinned copper braided cable 250V 200°C • Optional: EPD116760A | | |
| Length: 1000 mm ±10% | | Tubing: None |
| Connector: N/A | | |
| Color | Function | Pin |
| Red | Supply | |
| Black | 0V | |
| Green or Blue | CAN High | |
| White | CAN Low | |
| Braid (not for EPD116760A) | - | |

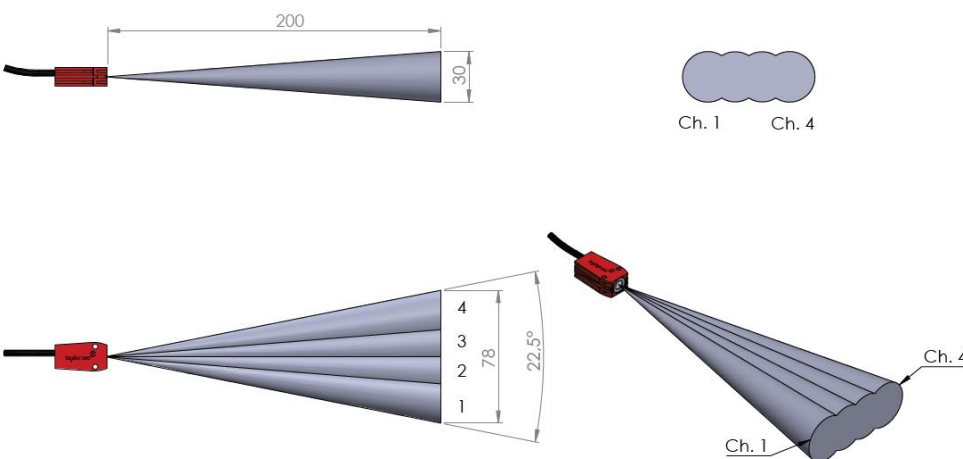
FOV (Field of view)

41.6° FOV version:

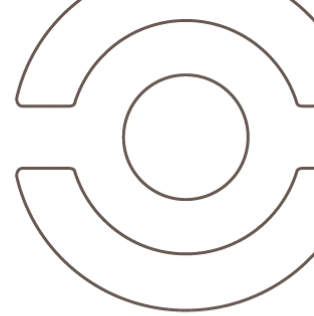


| Distance | Ø target per channel | Total width |
|----------|----------------------|-------------|
| 50 mm | 15 mm | 40 mm |
| 100 mm | 19 mm | 75 mm |
| 150 mm | 24 mm | 112 mm |
| 200 mm | 30 mm | 152 mm |
| 300 mm | 45 mm | 228 mm |
| 400 mm | 60 mm | 304 mm |

22.5° FOV version:



| Distance | Ø target per channel | Total width |
|----------|----------------------|-------------|
| 200 mm | 30 mm | 78 mm |
| 300 mm | 45 mm | 117 mm |
| 400 mm | 60 mm | 156 mm |
| 500 mm | 75 mm | 195 mm |
| 600 mm | 90 mm | 234 mm |
| 700 mm | 105 mm | 273 mm |
| 800 mm | 120 mm | 312 mm |



CAN data output

Frame #1 (default Tx Frame ID: 0x03F0)

| ID | Byte 0 | Byte 1 | Byte 2 | Byte 3 | Byte 4 | Byte 5 | Byte 6 | Byte 7 |
|--------|----------------------|------------------|----------------------|------------------|----------------------|------------------|----------------------|------------------|
| 0x03F0 | Channel 1 MSB | Channel 1 LSB | Channel 2 MSB | Channel 2 LSB | Channel 3 MSB | Channel 3 LSB | Channel 4 MSB | Channel 4 LSB |
| | Resolution: 0.1°/bit | | Resolution: 0.1°/bit | | Resolution: 0.1°/bit | | Resolution: 0.1°/bit | |

Changing parameters

Must be setup according to Texense CAN protocol, or by using the tWist® software (texense Windows software tool) with the tSIB (texense Smart Interface Box).

| Address | Parameter | Raw values | Values | Comments | |
|---------|------------------------------|--------------|----------------------|--|----------------|
| 0x00 | Baudrate | 0x00 | 1000 Kbps | Default | |
| | | 0x01 | 500 Kbps | - | |
| | | 0x02 | 250 Kbps | | |
| | | 0x03 | 125 Kbps | | |
| 0x01 | Emission frequency | 0x02 | 10 Hz | Default | |
| | | 0x03 | 1 Hz | - | |
| | | 0x04 | Rx frame trig | On trig - 10Hz max. | |
| 0x02 | Rx frame ID | 0 to 0x07 | 0x0000 to 0x07F0 | MSB | Default 0x07F0 |
| 0x03 | | 0 to 0xFF | | LSB | |
| 0x04 | Tx frame ID | 0 to 0x07 | 0x0000 to 0x07F0 | MSB | Default 0x03F0 |
| 0x05 | | 0 to 0xFF | | LSB | |
| 0x08 | Degree Unit | 0 | Fahrenheit | - | |
| | | 1 | Celsius | Default | |
| 0x09 | Gain factor | 500 to 2000 | 1/1000 (0.5 to 2) | MSB | Default 1000 |
| 0x0A | | | | LSB | |
| 0x0B | Digital filter response time | 100 to 10000 | ms (0.1 to 10s) | MSB | Default 400 ms |
| 0x0C | | 0: disable | | LSB | |
| 0x0D | Dynamic compensation | 0 | OFF | Compensation for quick changes in ambient (sensor) Temperature | |
| | | 1 | ON | | |

For complete information, contact us at info@texense.com

Ordering information

Ordering ref:

IRN4C-F1-Range-V2-FOV - Distance - R120

140: Range 140°C

200: Range 200°C

22.5: FOV 22.5°

41.6: FOV 41.6°

Calibration distance in mm

Optional 120Ω termination resistor

ex: IRN4C-F1-200-V2-41.6-200